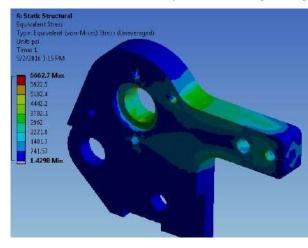
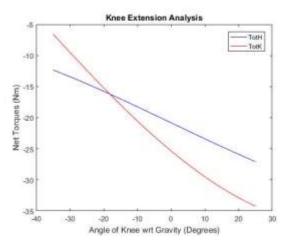
# Muscle-Powered Walking Exoskeleton for People with Spinal Cord Injury

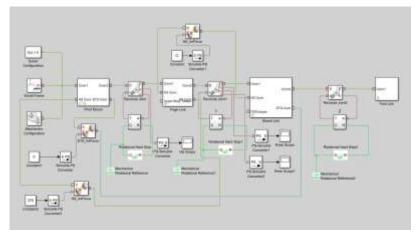
- Designed a system which uses a combination of electrical stimulation and mechanical orthosis to enable gait
- Fabricated and bench tested the exoskeleton
- Performed a pilot study using one volunteer with spinal cord injury to demonstrate the feasibility of the exoskeleton

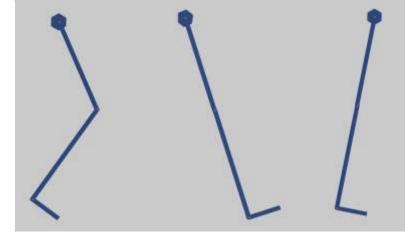
Analysis of the design using ANSYS and MATLAB





Simulink model of exoskeleton





# Design Fabricate Bench Test Pilot Test









### **Self-Fabricated Parts**













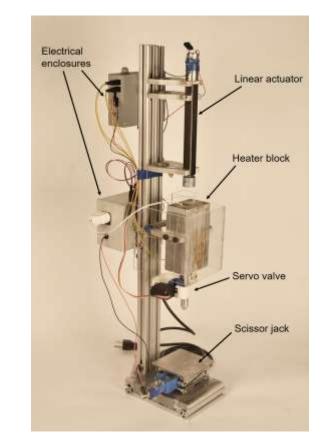


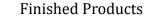




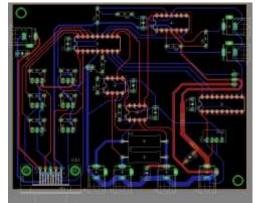
### The Mini-Molder

- Designed and fabricated an automatic Mini Injection Molder that can create any shaped object out of wax
- Designed a circuit to interface with sensors and actuators
- Created a PCB for the electronics
- Created a GUI using Python









**PCB** Layout

GUI

MINI

MOLDER

Lover Star

Raise

Manufelolder

Soch Temp (C)

Auto Mode Set Temperature Rei Auto Malting

Draining

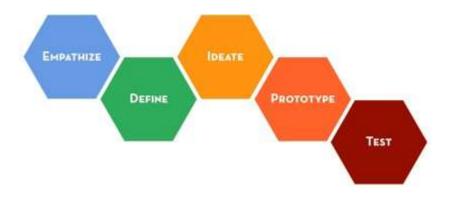
Plunger Clanent (A) Jack Clanent (A)

### A Non-Invasive Medical Device to Treat Lower Back Pain

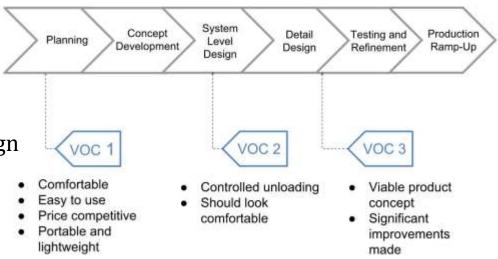




- Worked as a part of a cross-functional team to design a user-friendly, price competitive, and portable device that applies traction to the user's lower back while in a seated position
- Conducted multiple rounds of voice of customer interviews to gather user needs as well as to improve the design
- Analysed the market and drafted a business plan which we then pitched to the client and other entrepreneurs
- Drafted a provisional patent for the final design
- Collaborated with FDA to finalize the class of the device

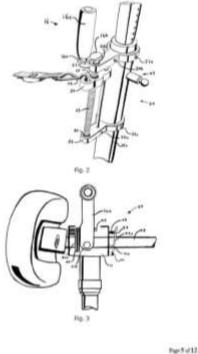


### **Customer Insights**



Seat Adjustment	Weight	LTX Strap (Status Quo)	Mechanical	Strap 2.0	Air Bladder
Control	2	0	2	1	0
Weight	1	0	-2	-1	0
Cost	1	0	-2	-1	-2
Ease of Use	1	0	2	1	1
Totals		0	2	1	-1
Arms (Rib Movement)	Weight	Pivoting (Status Quo)		Sliding w/Friction	Ratchet w/Teeth
Tuning	1	0	-2	0	0
Durability	0.5	0	0	-1	-1
Cost	1	0	2	2	1
Ease of Use	1	0	-1	1	1
Totals		0	-1	2.5	1.5

### Pugh Chart for Design Decisions



### **Provisional Patent Draft**

#### Field of the Invention

This invariants refers parametry to an apparents for transforming the stress and lowing times the insulant spins to the driving of an analysis which provides baseling the stress real lowing the spins. These specifically, the lowestim transformed the drive from the hardware spins to the driving stabilistic the former of generation with the stress processes summal stration and lowing of the instruct spins and its component. This drives utilizer a support which drives the stress and a start shall have been stress and its component. This drives utilizer a support which drives the transmission and a start shall have been stress and the component. This drives utilizer a support which making a positive line in the stress provides and a stress and the stress are drives and from component. The drives produces making a positive line in drives provides on a popuration in a stress are drives in the drives and drives are stress of stress drives are stress of the insulance spins. The art by which this intensions was driven granted the stress drives drives are stress of the insulance spins. The stress drives are drives are drives are drives are there are also are drives are provides are stress of the insulance spins. The drives are spins.

#### **Background of the Investion**

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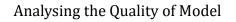
#### humanary of the Investion

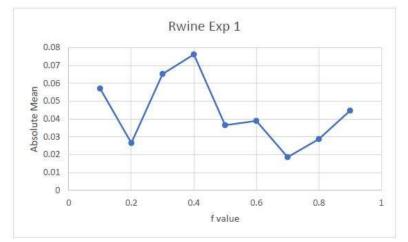
The protect accuration is a structure data relach and/ode a badget adjustative user wells accompanying tracts support annulates full volt topplet so adjust the test to decompany for landator space for the proper of low bad prior bed. Volks is upon et. the bats append nativative in the pointer investors and income opport mode to the decompanying of the prior of the source of the source of the source of the source opport and low prior at his bad wells the source of the source of the source of the source opport and and the source of the source opport and companying on the source of the source of the source of the source of the source opport and companying on the source opport and the source of the source of the source opport and companying on the source opport and the source of the source opport and the source opport and the source of the source of the source of the source opport and the source opport and the source opport and the source opport and the source of the source opport and the source opport and the source of the source of the source of the field to test a class of adjustation of the height of trace sources opports and the source of the source of the field to test a class of adjustation of the height of trace sources opports and the source of the source of the source opport and th

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# Data Modelling Using R

- Developed multifactor linear regression models using • a standard statistical approach
- Implemented data cleaning, sanity checking, training ٠ and testing on various data sets using R
- Created a linear model that predicts the quality of • wine based on the various constituents





Rwine Exp 2

0.4

f value

0.6

0.8

0.07

0.06

0.03

0.02

0.01

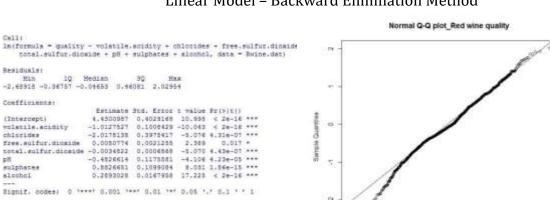
0

0

0.2

0.05 0.04

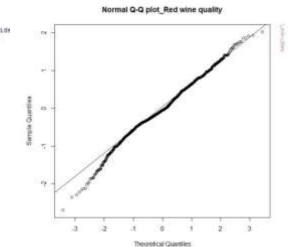
Absolute



Residual standard error: 0.6477 on 1591 degrees of freedom Multiple R-squared: 0.3595, Adjusted R-squared: 0.3567 F-statistic: 127.6 on T and 1591 DP, p-value: < 2.2e-16

Call:

pH.

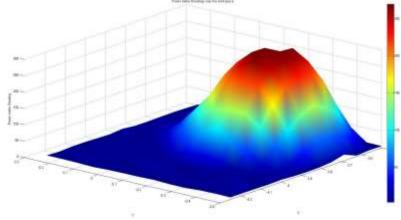


Linear Model – Backward Elimination Method

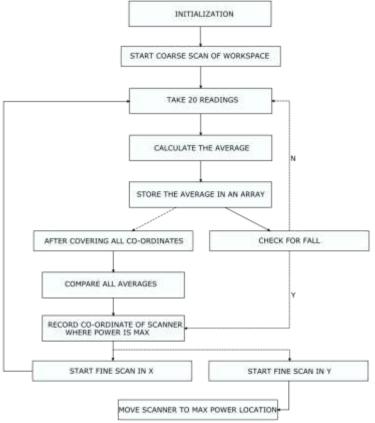
### Automation of Laser Fiber Alignment

- Developed an algorithm for automatic alignment of the laser with an optical fiber which reduced the set up time from 20 min to 3 min
- Designed a focusing unit and assembled the experimental setup
- Experimentally evaluated laser ablation on agaragar and verified the performance of the algorithm

Testing and Validation





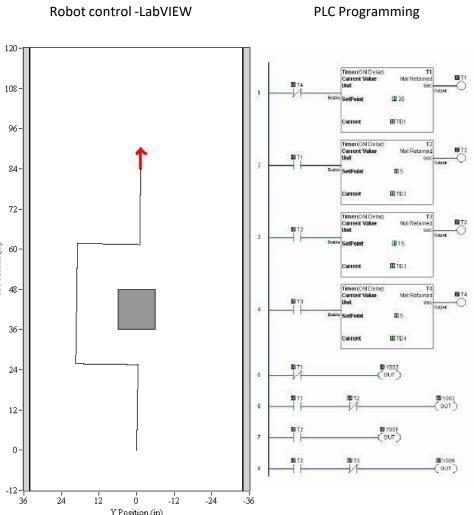


Algorithm logic

### Teaching Assistant – Motion Control Laboratory

- Helped students improve their C programming skills and guided them through the various lab topics
- Lab topics included-
  - Analog to digital, digital to analog conversion

  - Conversion Implementing digital IIR and FIK IIICLE Determining frequency response of a servo (1) Conversion ٠
  - Using Simulink to design control system
  - Ladder logic programming
  - Using LabVIEW to control a robot
- Graded the assignments and exams
- Helped maintain the equipment in the lab (oscilloscopes, DAC's etc.)



### The E-Board



Assisted the development of a self propelled electric snowboard prototype

